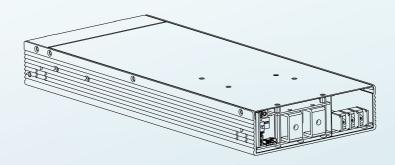


### Bidirectional Power Supply

· High efficiency · Lightweight · Intelligent



The BIC-2200 is a 2.2KW bidirectional power supply with energy recycle function. It is fully digital and 1U height designed. It is designed to control the power transferred from AC grid to DC and DC to AC grid for energy recycle. The implementation of a bidirectional power supply of the BIC-2200 allows battery manufactures to charge the battery from AC grid and recycle the DC energy back into AC grid in one single unit. With built-in functions such as active current sharing, remote ON/OFF control and optional CANbus protocol, the BIC-2200 provides vast design flexibility for battery formation & test equipment, V2G(Vehicle-to-grid) system, charging station, laser system and kinetic recovery system.

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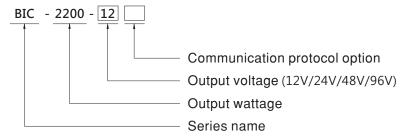
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### 1. Safety Guidelines

- Risk of electrical shock and energy hazard, all failure should be examined by a qualified technician. Please do not remove the case form the bidirectional power supply by yourself.
- Please do not install the supply in places with high moisture, high ambient temperature or under direct sunlight.
- The AC voltage range is 180 260Vac (47 63Hz), please do not connect the supply to AC gird out of the range.
- Fans and ventilation holes must be kept free from any obstructions. At least 15 cm clearance must be kept when the adjacent device is a heat source.
- Please do not stack any object on the unit.
- The safety protection level of this supply is class I. The "Frame Ground"(\(\ddot\)) of the unit must be well connected to PE (Protective Earth).

### 2.Introduction

### 2.1 Model Encoding



Type	Communication Protocol	Note
Blank	None protocol	In Stock
CAN	CANBus protocol	By request

#### 2.2 Features

- 1U low profile design
- Full digital design with 93% conversion efficiency for both AC/DC and DC/AC conversion
- Ultrafast switching time between AC/DC and DC/AC of 1ms.
- CB/UL/TUV CB/TUV/UL 62368-1 certified, and design refer to IEC 62477 regulation
- Active current sharing up to 11000W(4+1)
- <3% Low THDi in both conversion mod</li>
- Force charging and discharging mode with CANBus command (Optional)
- Complete protections: Anti-islanding protection, AC fail protection, DC OVP,OLP, OCP, OTP
- 5 years warranty

# 2.3 Specification

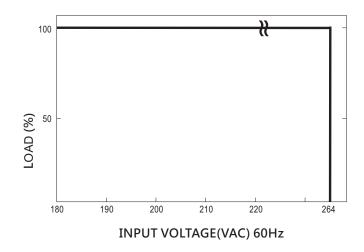
MODE	L		BIC-2200-1	2	BIC-2200-24	BIC-2200-48	BIC-2200-96		
		DC VOLTAGE	12V		24V	48V	96V		
		RATED CURRENT	180A		90A	45A	22.5A		
		RATED POWER	2160W						
		FULL POWER VOLTAGE RANGE	12 ~ 15V		24 ~ 28V	48 ~ 65V	96 ~ 112V		
	E	RIPPLE & NOISE (max.) Note.2	160mVp-p		260mVp-p	300mVp-p	480mVp-p		
	OUTPUT	VOLTAGE ADJ. RANGE	10 ~ 15V		19 ~ 28V	38 ~ 65V	76 ~ 112V		
	8	CURRENT ADJ. RANGE	0 ~ 180A		0 ~ 90A	0 ~ 45A	0 ~ 22.5A		
e o		VOLTAGE TOLERANCE Note.3	±1.0%		±1.0%	±1.0%	±1.0%		
ecti		LINE REGULATION	±0.5%		±0.5%	±0.5%	±0.5%		
ä		LOAD REGULATION	±0.5%		±0.5%	±0.5%	±0.5%		
AC to DC Direction		SETUP, RISE TIME	1800ms, 60	1800ms, 60ms/230VAC at full load					
AC t		AC VOLTAGE RANGE	180 ~ 264\						
1		FREQUENCY RANGE	47 ~ 63Hz						
		POWER FACTOR (Typ.)	0.98/230V	AC at full load	<u> </u>				
	5	EFFICIENCY (Typ.) Note.5	90%		93%	93%	93%		
	INPUT	AC CURRENT (Typ.)	11A/230VA	C					
		INRUSH CURRENT (Typ.)		RT 35A/230\	VAC				
		LEAKAGE CURRENT	<2mA/230						
		TOTAL HARMONIC DISTORTION		d=100%/230	VAC)				
	6.	RATED, INPUT POWER	1800W						
	lote	FULL POWER VOLTAGE RANGE	12 ~ 15V		24 ~ 48V	48 ~ 65V	96 ~ 112V		
DC to AC Direction	NPUT (Note.9)	DC VOLTAGE RANGE	10 ~ 15V		19 ~ 28V	38 ~ 65V	76 ~ 112V		
	M	MAX. INPUT CURRENT	150A		75A	37.5A	18.75A		
	_	RATED OUTPUT POWER (Typ.) (@230V, 50Hz							
		VOLTAGE RANGE	180 ~ 264VAC						
o AC	-	FREQUENCY RANGE	47 ~ 63Hz						
S	OUTPUT	AC CURRENT (Typ.)	7.5A/230V/						
_	8	POWER FACTOR (Typ.)	0.99/230V	AC at full load	<u> </u>				
		, ,	90.5%		93%	93%	93%		
		TOTAL HARMONIC DISTORTION	<3% (@loa	id>100%/230	OVAC)				
			105 ~ 115% rated output power						
		OVER LOAD	AC to DC		urrent limiting, shut do e-power on to recover		ec. after DC O/P voltage is		
			DC to AC	Not accura	ible with constant pov	ver design			
		SHORT CIRCUIT			re-power on to recove				
PROTE	CTION		17.6 ~ 20.8		33.6 ~ 39.2V	72.6 ~ 86V	134 ~ 157V		
		OVER VOLTAGE			own O/P voltage, re-p				
		OVER TEMPERATURE				y after temperature goe	es down		
		ISLANDING PROTECTION	Shut down	AC O/P volt	age, re-power on to re	ecover			
		REMOTE ON-OFF CONTROL	By electrical	By electrical signal or dry contact Short: Power ON Open: Power OFF Please refer to the Function Manual infollowing					
BIDIRECTION SWITCH TIME(Typ. ALARM SIGNAL		BIDIRECTION SWITCH TIME(Typ.)		-					
			Isolated TT		out for T-Alarm, DC-Ob				
FUNC	TION	AUXILIARY POWER			5%, ripple 150mVp-p				
		=		160A	80A	40A	20A		
		D. 1775 D. 1750	AC to DC		usted by communication		1 ==::		
		BALLERY MODE RATED							
		BATTERY MODE RATED CURRENT(default) Note.7		120A	64A	32A	16A		

3

MODEL		BIC-2200-12	BIC-2200-24	BIC-2200-48	BIC-2200-96		
	WORKING TEMP.	-30 ~ +70°C (Refer to "D	erating Curve")				
	WORKING HUMIDITY	20 ~ 90% RH non-condensing					
ENVIRONMENT	STORAGE TEMP., HUMIDITY	-40 ~ +85°C, 10 ~ 95% F	RH non-condensing				
	TEMP. COEFFICIENT	±0.03%/°C (0 ~ 45°C)					
	VIBRATION	10 ~ 500Hz, 2G 10min./	1cycle, 60min. each a	long X, Y, Z axes			
	SAFETY STANDARDS	UL62368-1, CAN/CSA C (by request) approved	22.2 No.62368-1,TU	V BS EN/EN62368-	1, EAC TP TC 004, IEC62477-1		
	WITHSTAND VOLTAGE Note.8	I/P-O/P:3KVAC I/P-FG:2KVAC O/P-FG:500VAC					
	ISOLATION RESISTANCE Note.8	I/P-O/P, I/P-FG, O/P-FG	:100M Ohms / 500VI	0C / 25°C / 70% RH			
		BS EN/EN55032					
		Parameter	Standard		Test Level / Note		
		Conducted	BS EN/ENS	5032 (CISPR32)	Class B		
	EMC EMISSION	Radiated	BS EN/ENS	5032 (CISPR32)	Class A		
		Harmonic Current	BS EN/EN6	1000-3-2	Class A		
SAFETY & EMC		Voltage Flicker	BS EN/EN6	1000-3-3			
(Note 4)		BS EN/EN55035, BS EN	I/EN61000-6-2				
(11010 4)		Parameter Standard		Test Level / Note			
		ESD	BS EN/EN6	1000-4-2	Level 3, 8KV air ; Level 2, 4KV contact		
		Radiated	BS EN/EN6	1000-4-3	Level 3		
	EMC IMMUNITY	EFT / Burst	BS EN/EN6	1000-4-4	Level 3		
		Surge	BS EN/EN6	1000-6-2	2KV/Line-Line 4KV/Line-Earth		
		Conducted	BS EN/EN6	1000-4-6	Level 3		
		Magnetic Field	BS EN/EN6	1000-4-8	Level 4		
		Voltage Dips and Interru	ptions BS EN/EN6	1000-4-11	>95% dip 0.5 periods, 30% dip 25 periods, >95% interruptions 250 periods		
	MTBF	155.56K hrs min. Teld	cordia SR-332 (Bello	ore); 46K hrs min.	MIL-HDBK-217F (25°C)		
OTHERS	DIMENSION	330*140*41mm (L*W*H)	)				
	PACKING	2.9Kg; 4pcs/12.6Kg/1.2	5CUFT				
NOTE	<ol> <li>All parameters NOT specially mentioned are measured at 230VAC input, rated load and 25°C of ambient temperature.</li> <li>Ripple &amp; noise are measured at 20MHz of bandwidth by using a 12" twisted pair-wire terminated with a 0.1uf &amp; 47uf parallel capacitor.</li> <li>Tolerance: includes set up tolerance, line regulation and load regulation.</li> <li>Need additional EMI filter to meet regulations of EMC conducted and radiated emission. Characteristics of EMI filter please refer to the table, minimum insertion loss.</li> <li>The efficiency is measured at 75% load.</li> <li>The ambient temperature derating of 5°C/1000m with fan models for operating altitude higher than 2000m(6500ft).</li> <li>CANBus model only.</li> <li>During withstandards voltage and isolation resistance testing, the screw "A" shall be temporarily removed, and shall be istalled back after the testing.</li> <li>As a constant power output, the driver will auto derating the current limitation when voltage raise above rated voltage(12V,24V,48V,96V) in order to remain 1800W output. On the other hand, when voltage is below rated voltage(12V,24V,48V,96V), the maximum current limitation will set at Max input current.</li> <li>Product Liability Disclaimer: For detailed information, please refer to https://www.meanwell.com/serviceDisclaimer.aspx</li> </ol>						

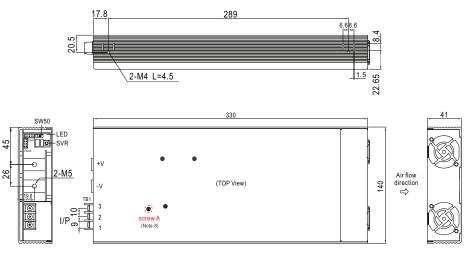
## 2.4 Derating curve

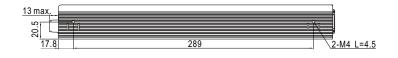
# -30 -20 0 15 40 45 60 70 (HORIZONTAL) AMBIENT TEMPERATURE (°C)

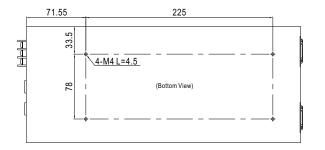


## 2.5 Mechanical specification

Unit:mm







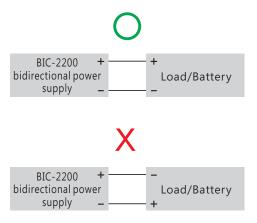
### 3.Installation & Wiring

#### 3.1 Precautions

- Please make sure the system chassis has sufficient strength to carry the unit.
- In order to ensure the lifespan of the unit, you should refrain from operating the unit in environment of high dust or moisture.
- The bidirectional power supply is designed with built-in DC fans, please make sure the ventilation is not blocked. There should be no barriers within 15cm of the ventilating

### 3.2 Installation Procedures

- ① Choose the right and suitable cable size for connection between the BIC-2200 and the loads or batteries. Please refer to 3.3 DC cable size selection.
- ② Connect the DC positive polarity of the supply to the positive of the loads/batteries and connect the DC negative polarity of the supply to the negative of the loads/batteries. Make sure there is no reverse polarity or short-circuit on the connection.



③ Connect the supply to the AC grid, FG to the earth, AC/N to the neutral and AC/L to the live.

NOTE: The bidirectional power supply is single-phase input/output. Please pay attention to the wiring when connecting the supply to a three-phase system.

#### 3.3 DC Cable Size Selection

Wire connections should be as short as possible and less than 1 meter is highly recommended. Make sure that suitable wires are chosen based on safety requirement and rating of current. Small cross section will result in lower efficiency, less output power and the wires may also become overheated and cause danger. For selection, please refer to table 3-1.

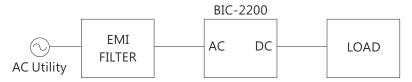
AWG	Cross-section Are(mm²)	DC current (A)
8	6	32A ~ 40A
6	10	40A ~ 63A
4	16	63A ~ 80A
2	25	80A ~ 100A
1	35	100A ~ 125A
	30	139A
	50	190A
	60	217A
	80	257A

Table 3-1 Wire recommendations

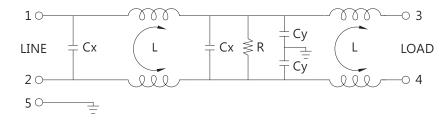
### 3.4 External filter

To meet regulations of EMC conducted and radiated emission, adding an additional EMI filter is needed. Please refer to configuration below and characteristics for suggested filters.

### 3.4.1 Configration



#### 3.4.2 Schematic



L	Сх	Су
0.6mH	1.0uF	10000pF

# 3.4.3 Minimum insertion loss (In dB at $50\Omega$ system) : Filter model 30DPGS5C or equivalent

FREQ. MHz	0.01	0.05	0.10	0.15	0.50	1.0	5.0	10	30
COM. MODE dB	2	5	8	10	30	35	55	45	30
DIF. MODE dB	4	15	18	18	45	50	40	40	40

### 4. User Interface

### 4.1 Panel Description

(A) Ventilation holes for fans:

The supply requires suitable ventilation to work properly. Please make sure there is sufficient ventilation and the lifespan of the supply can preserved.

**B** LED indicator:

Indicate the status of supply and the load condition.

© SVR:

For DC voltage setting.

DIP switch:

For device addressing when using the communication interface.

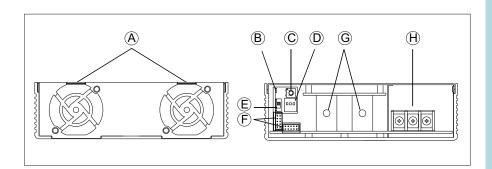
(E) SW50:

Used to stabilize parallel signals when multi-supplies in parallel connection.

F Function pins:

They are used for control and monitoring functions. Please refer to 4.3 and 4.4.

- **G** DC terminals
- (H) AC terminals

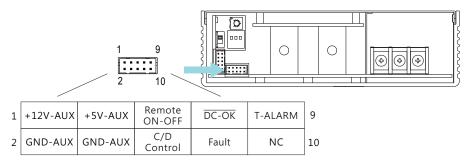


### 4.2 LED Indicator

The LED indicator is controlled by the microcontroller or the MCU. The MCU will change color of the indicator according to its operation status. The indicator lights in constant green when the supply is in operating mode; The indicator's flashing in green when the supply is in recycle mode; The indicator turns red when the supply is in abnormal conditions or protection mode.

LED Indicator	Status
<ul><li>Green</li></ul>	Operating (AC to DC, work as an ordinary power supply or charger)
Green (Flashing)	Recycle (DC to AC, work as a grid tie inverter)
<ul><li>Red</li></ul>	Abnormal (OTP, OLP, fan-lock, etc)

### 4.3 Pin Assignment of CN46



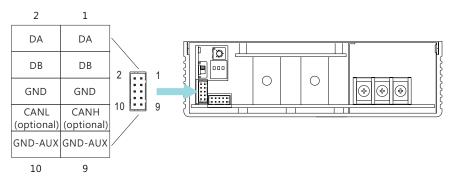
Pin No.	Function	Description
1	+12V-AUX	Auxiliary voltage output, 11.4~12.6V, referenced to GND-AUX (pin 2,4). The maximum output current is 0.5A. This output is not controlled by the Remote ON/OFF control.
2,4	GND-AUX	Auxiliary voltage output GND. The signal return is isolated from the output terminals (+V & -V).
3	+5V-AUX	Auxiliary voltage output, 4.5~5.5V, referenced to GND-AUX (pin 2,4) only for Remote ON/OFF used. This output is not controlled by the Remote ON/OFF control.

Pin No.	Function	Description
5	Remote ON-OFF	The unit can turn the output ON/OFF by electrical signal or dry contact between Remote ON/OFF and +5V-AUX(pin 3). (Note.1)
6	C/D Control (Note.2)	High (4.5 ~ 5.5V): Battery Charging mode Low (-0.5 ~ 0.5V): Battery Discharging mode (Note.1)
7	DC-OK	High (4.5 ~ 5.5V): When the Vout≦80%±5%. Low (-0.5 ~ 0.5V): When Vout≧80%±5%. The maximum sourcing current is 4mA and only for output.
8	Fault	High (4.5 ~ 5.5V): When the Vac ≤ 165Vrms,OLP, SCP,OTP,OVP,AC Fail,fan lock,islanding protection.  Low (-0.5 ~ 0.5V): When Vac≥175Vrms and when power supply work normally.  The maximum sourcing current is 4mA and only for output.  (Note.1)
9	T-ALARM	High (4.5 ~ 5.5V): When the internal temperature exceeds the limit of temperature alarm, or when any of the fans fails.  Low (-0.5 ~ 0.5V): When the internal temperature is normal, and when fans work normally.  The maximum sourcing current is 4mA and only for output. (Note.1)
10	NC	

Note 1: Isolated signal, referenced to GND-AUX.

Note 2: CANBus model only.

# 4.4 Pin Assignment of CN47



Pin No.	Function	Description
1,2	DA	Differential digital signal for parallel central (Note 1)
3,4	DB	Differential digital signal for parallel control. (Note.1)
5,6	GND	Negative output voltage signal. Certain function reference. It can not be connected directly to the load.
7	CANH (optional)	For CANBus model: Data line used in CANBus interface. (Note.2)
8	CANL (optional)	For CANBus model: Data line used in CANBus interface. (Note.2)
9,10	GND-AUX	Auxiliary voltage output GND. The signal return is isolated from the output terminals (+V & -V).

Note 1: Non-isolated signal, referenced to GND. Note 2: Isolated signal, referenced to GND-AUX.

### 4.5 Function Description of SW50

Parallel connection of the BIC-2200 is by digital differential signals. Units in parallel compensate and stabilize their output through the digital parallel signals. SW50 is a termination resistor which is used to prevent signal reflections, then increasing communication quality. For the usage of SW50, please refer to 5.9 Current Sharing.

### 4.6 Function Description of DIP Switch

Each unit should have their unique and own device address to communicate over CANBus. Please be aware that: This DIP switch only takes effect when the communication interface is used. It is not necessary to set this switch in general use. For details, please refer to 5.10.2 CANBus addressing.

5

### 5. Operation

BIC-2200 possesses AC to DC and DC to AC two way conversion functions. The conversion direction can be automatically detected and controlled by BIC-2200's internal firmware or manually switched by users according to different application requirements. Before entering detailed function explanation. Please refer to following definitions.

AC to DC (Energy absorbing and charging/ power supplying):

The BIC-2200 converts AC energy from the grid into DC energy for the battery or the loads. The operation principle is the same as an ordinary power supply or a charger.



DC to AC (Energy recycling and discharging):

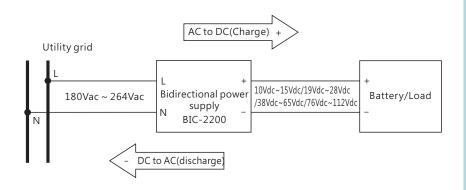
Opposite to the AC to DC conversion, the BIC-2200 converts DC energy from the battery or loads into AC energy, then feeding back to the grid. AC output synchronization range is 180Vac~264Vac/47Hz~63Hz, the bidirectional power supply can work normally as long as the AC gird is within the range.



### 5.1 Description of Bidirectional Operation

#### 5.1.1 Overview

The output range of the BIC-2200 covers DC: 10V - 112V; AC: 180 - 264Vac / 47-63Hz, which can be used to applications with various voltage requirements, such as battery test equipment. To cope with different application occasions, there are two modes for selection, bi-direction auto-detect mode and programmable bi-direction battery mode.



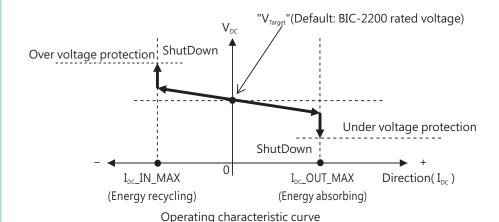
#### 5.1.2 Bi-direction auto-detect mode

This is the default factory setting, AC to DC or DC to AC conversion is controlled by BIC-2200 automatically according to operation mechanism below.

- "Target voltage" is the DC voltage setting of the bidirectional supply, when the DC end voltage is different from the "target voltage", the internal firmware will switch between two conversion functions of AC to DC or DC to AC. "Target voltage" is adjustable by the SVR.
- When the "target voltage" is higher than the battery voltage or application equipment voltage, the BIC-2200 operates in AC to DC conversion.
- When the "target voltage" is lower than the battery voltage or application equipment voltage, the BIC-2200 operates in DC to AC conversion.

NOTE: During this mode, AC to DC or DC to AC conversion is judged by the internal firmware. Active control signal (e.g. C/D control) will not take effect in this mode.

Condition	Conversion
$V_{\text{Target}} > V_{\text{DC}}$	AC to DC
$V_{Target} > V_{DC}$	DC to AC

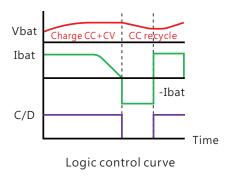


#### 5.1.3 Bi-direction battery mode

This is an optional mode, which must work with CANBus communication interface. To activate the mode, please follow below:

- 1. Set command SYSTEM\_CONFIG(0x00C2) at 0x0003 → Activate CANBus communication mode.
- 2. Set command BIDIRECTIONAL\_CONFIG(0x00C2) at 0x0001  $\rightarrow$  Set at bi-direction battery mode.
- 3. Repower on the supply to activate the battery mode NOTE: For detailed CANBus information, please refer to 5.10 CANBus Protocol

After bi-direction battery mode is activated, users can switch the supply between AC to DC or DC to AC conversion by CANBus command (digital) or C/D control (analogy). Please refer to 5.1.3.1 CANBus command (digital) and 5.1.3.2 C/D control (analogy)



#### 5.1.3.1 CANBus command (digital)

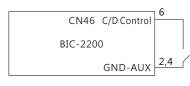
The users can set the supply in AC to DC (charging) or DC to AC (discharging) conversion directly through command DIRECTION\_CTRL (0x0100). Command VOUT\_SET(0x0020) and IOUT\_SET(0x0030) are used to adjust values of charge voltage and charge current in AC to DC conversion. Command REVERSE\_VOUT\_SET(0x0120) REVERSE\_IOUT\_SET(0x0130) are used to adjust values of discharge voltage and discharge current in DC to AC conversion.

Command	Conversion
DIRECTION_CTRL = 00h	AC to DC(charge)
DIRECTION_CTRL = 01h	DC to AC(discharge)

NOTE: Please refer to 5.10.4 CANBus value range and tolerance for detailed information about adjustable ranges of VOUT\_SET, IOUT\_SET, REVERSE\_VOUT\_SET and REVERSE\_IOUT\_SET.

#### 5.1.3.2 C/D Control (analogy)

The users also can control AC to DC (charge) or DC to AC (discharge) conversion via analogy signals.



	C/D control to GND-AUX	Conversion		
,	C/D control = 4.5 – 5.5V	AC to DC(charge)		
	C/D control = -0.5 – 0.5V	DC to AC(discharge)		

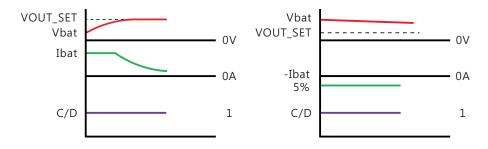
NOTE: Analogy signals cannot be used to adjust parameters of charging voltage (VOUT\_SET)/discharging voltage (REVERSE\_VOUT\_SET) and charging current (IOUT\_SET)/discharge current (REVERSE\_IOUT\_SET), but only control AC to DC or DC to AC conversion.

# 5

#### 5.1.3.3 Notes on battery mode

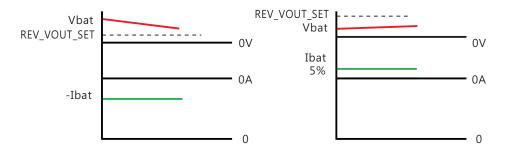
In bi-direction battery mode, although users can determine direction of the conversions on their demand, however if the setting voltage does not match the actual DC end voltage, AC to DC (charging) or DC to AC (discharging) conversion may not work as expected. Here are examples that will cause conversion errors.

- 1. During AC to DC conversion (C/D control = High or DIRECTION\_CTRL = 00h), if battery voltage is higher than the value of command VOUT\_SET (charge voltage), the BIC-2200 will perform DC to AC conversion instead, but limiting discharge current at 5% of rated current. If you want to ensure AC to DC conversion working properly, please make sure value of command VOUT\_SET is higher than the battery voltage.
- 2. During DC to AC conversion (C/D control =Low or DIRECTION\_CTRL = 01h), if battery voltage is lower than the value of command VOUT\_SET\_REV, the BIC-2200 will perform AC to DC conversion instead, but then limiting charge current at 5% of rated current. To ensure DC to AC conversion working properly, please make sure value of command VOUT\_ SET\_REV is lower than the battery voltage.



VOUT SET higher than Vbat and C/D=1

VOUT\_SET lower than Vbat and C/D=1



REV\_VOUT\_SET lower than Vbat and C/D=0

REV VOUT SET higher than Vbat and C/D=0

### 5.2 Inrush Current Limiting

- Built-in AC inrush current limiting circuit
- Since the inrush current limiting circuit mainly consists of a NTC thermistor and a relay, inrush current will be much higher than the specified value if the thermistor in AC side is not allowed sufficient time to cool down. After turning off the supply, a 10 second cool down period is recommended before turning on again.

### 5.3 Power Factor Correction (PFC)

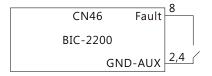
Built-in active power factor correction (PFC) function, power factor (PF) will be 0.95 or better at full load condition in AC to DC or DC to AC conversion. PF will be less than 0.95 if it is not at full load condition during AC to DC or DC to AC conversion.

### 5.4 Fan Speed control

• Built-in fan speed control circuit, fan speed changes automatically depending on internal temperature.

### 5.5 Fault Signal

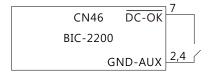
- Fault signal is used to inform application equipment that whether it is energy recyclable. When it is OLP, SCP or OTP, BIC-2200 will send a high level of fault signal 100ms in advance to notify the application before shutting down the supply. A fault signal will send out at the same time of shutting down operation in the reset of protection (e.g. AC fail).
- Maximum output current 4mA.



CN46 Fault to GND-AUX	Condition
-0.5~0.5V	Normal working
4.5~5.5V	Not energy recyclable

### 5.6 (DC-OK) Signal

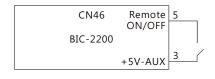
- Built-in DC output voltage detection circuit.
- Maximum output current 4mA.



CN46 DC-OK to GND-	Condition
-0.5~0.5V	DC OK
4.5~5.5V	Abnormal in DC

#### 5.7 Remote Control

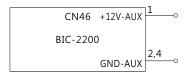
- Built-in remote ON/OFF control circuit, which is used to turn on/off the supply.
- Please be aware that "remote ON/OFF and "+5V-AUX" on CN46 should be linked together to allow the unit to operate normally; if kept open, there will be no output.
- Maximum input voltage 5.5V.



CN46 Remote ON/OFF to +5V-AUX	Condition
-0.5~0.5V	ON
4.5~5.5V	OFF

### 5.8 Auxiliary Output

• Built-in 12V/0.5A auxiliary output



CN46+12V-AUX to GND-AUX	Condition
PIN1-PIN2,4	12Vdc

### 5.9 Parallel Operation

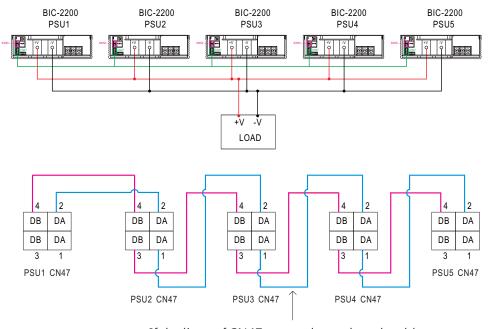
BIC-2200 has the built-in active current sharing function and can be connected in parallel, up to 5 units, to provide higher output power as exhibited below:

- The power supplies should be paralleled using short and large diameter wiring and then connected to the load.
- In parallel connection, power supply with the highest output voltage will be the master unit and its Vout will be the DC bus voltage.
- The total output current must not exceed the value determined by the following equation:
  - Maximum output current at parallel operation=(Rated current per unit) x (Number of unit) x 0.95
- When the total output current is less than 5% of the total rated current, or say (5% of Rated current per unit) x (Number of unit) the current shared among units may not be balanced.
- Under parallel operation ripple of the output voltage may be higher than the SPEC at light load condition, It will go back to normal ripple level once the output load is more than 5%.
- CN47/SW50 Function pin connection

Parallel	PS	U1	PS	U2	PS	SU3	PS	SU4	PS	SU5
i araner	CN47	SW50								
1 unit	Х	ON		_	_	_	_	_	_	_
2 unit	V	ON	V	ON	_	_	_	_	_	_
3 unit	V	ON	V	OFF	V	ON	_	_	_	_
4 unit	V	ON	V	OFF	V	OFF	V	ON	_	_
5 unit	V	ON	V	OFF	V	OFF	V	OFF	V	ON

(V: CN47 connected; X: CN47 not connected)

5



If the lines of CN47 are too long, they should be twisted in pairs to avoid the noise.

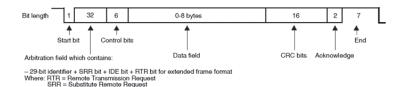
### $\odot$ DA ${}^{\backprime}$ DB Connected mutually in parallel

#### 5.10 CANBus Protocol

CANBus communication interface provides control and monitoring functions. It is helpful when users intent to modify the parameters remotely. Users can read and write the parameters through the bus, which includes bi-directional battery mode switch, ON/OFF, charge voltage/current, discharge voltage/ current, temperature, etc.

#### 5.10.1 CAN Bus Specification

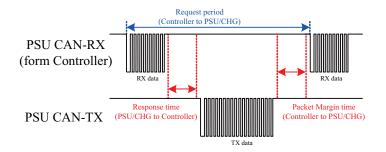
- Physical layer specification
   This protocol follows CAN ISO-11898 with Baud rate of 250Kbps.
- Data Frame
   This protocol utilizes Extended CAN 29-bit identifier frame format or CAN 2.0B.



• Communication Timing

IDE = Identifier Extension

Min. request period (Controller to BIC-2200): 20mSec Max. response time (BIC-2200 to Controller): 5mSec Min. packet margin time (Controller to BIC-2200): 5mSec



#### C

#### 5.10.2 CANBus Addressing

Each BIC-2200 unit should have their unique and own device address to communicate over the CANBus. PIN 1 - PIN 3 of the DIP switch allows users to designate an address for their supply units (with maximum of 8 addresses). Please refer to below for the detailed setup advice.



N 4 - al al NI -	DIP switch position				
Model No.	1	2	3		
0	ON	ON	ON		
1	ON	ON	OFF		
2	ON	OFF	ON		
3	ON	OFF	OFF		
4	OFF	ON	ON		
5	OFF	ON	OFF		
6	OFF	OFF	ON		
7	OFF	OFF	OFF		

#### 5.10.3 CANBus command list

Command Code	Command Name	Transaction Type	# of data Bytes	Description
0x0000	OPERATION	R/W	1	Remote ON/OFF control
0x0020	VOUT_SET	R/W	2	Charge voltage setting (format: value, F=0.01)
0x0030	IOUT_SET	R/W	2	Charge current setting (format: value, F=0.01)
0x0040	FAULT_STATUS	R	2	Summary status reporting
0x0050	READ_VIN	R	2	AC voltage reading value (format: value, F=0.1)
0x0060	READ_VOUT	R	2	DC voltage reading value Note. i(format: value, F=0.01)
0x0061	READ_IOUT	R	2	DC current reading value (format: value, F=0.01)
0x0062	READ_ TEMPERATURE_1	R	2	Internal ambient temperature (format: value, F=0.1)
0x0080	MFR_ID_B0B5	R	6	Manufacturer's name
0x0081	MFR_ID_B6B11	R	6	Manufacturer's name
0x0082	MFR_MODEL_B0B5	R	6	Manufacturer's model name
0x0083	MFR_MODEL_ B6B11	R	6	Manufacturer's model name
0x0084	MFR_REVISION_ B0B5	R	6	Firmware revision
0x0085	MFR_LOCATION_ B0B2	R/W	3	Manufacturer's factory location
0x0086	MFR_DATE_B0B5	R/W	6	Manufacturer's date
0x0087	MFR_SERIAL_B0B5	R/W	6	Product serial number

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Command Code	Command Name	Transaction Type	# of data Bytes	Description
0x0088	MFR_SERIAL_ B6B11	R/W	6	Product serial number
0x00C0	SCALING_FACTOR	R	2	Scaling ratio
0x00C1	SYSTEM_STATUS	R	2	System status
0x00C2	SYSTEM_CONFIG	R/W	2	System configuration
0x0100	DIRECTION_CTRL	R/W	1	A/D or D/A conversion control
0x0120	REVERSE_VOUT_ SET	R/W	2	Discharge voltage setting (format: value, F=0.01)
0x0130	REVERSE_IOUT_ SET	R/W	2	Discharge current setting (format: value, F=0.01)
0x0140	BIDIRECTIONAL CONFIG	R/W	2	Bidirectional mode configuration

#### Note:

The conversion of setting and reading values is defined as following:

Actual value = Communication reading value  $\times$  Factor (F value). Among them, Factor needs to refer to the definition of SCALING\_FACTOR in each model list. EX: VDC\_real (actual DC voltage) = READ\_VOUT x Factor.

If the Factor of READ\_VOUT of a certain model is 0.01, the communication reading value is 0x0960 (hexadecimal)  $\rightarrow$  2400 (decimal), then VDC\_real = 2400  $\times$  0.01 = 24.00V.

#### Message ID definition:

Description	Message ID
BIC-2200 to controller Message ID	0x000C02XX
Controller to BIC-2200 Message ID	0x000C03XX
Controller broadcasts to BIC-2200Message ID	0x000C03FF

Note: XX means the address of BIC-2200 (which can be assigned by the DIP switch, range from  $0x00 \sim 0x07$ )

#### FAULT\_STATUS:

High byte	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Definition								HV_OVP
Low byte	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Definition	HI_TEMP	OP_OFF	AC_FAIL	SHORT	OLP	OVP	ОТР	FAN_FAIL

#### Low byte:

Bit 0 FAN\_FAIL : Fan locked flag

0 = Fan working normally

1 = Fan locked

Bit 1 OTP: Over temperature protection

0 = Internal temperature normal

1 = Internal temperature abnormal

Bit 2 **OVP**: **DC** over voltage protection

0 = DC voltage normal

1 = DC over voltage protected

Bit 3 OLP: DC over current protection

0 = DC current normal

1 = DC over current protected

Bit 4 SHORT : Short circuit protection

0 = Shorted circuit do not exist

1 = Shorted circuit protected

Bit 5 AC\_FAIL : AC abnormal flag

0 = AC range normal

1 = AC range abnormal

Bit6 OP\_OFF : DC status

0 = DC turned on

1 = DC turned off

Bit7 HI\_TEMP: Internal high temperature protection

 $0 = Internal\ temperature\ normal$ 

1 = Internal temperature abnormal

### High byte:

Bit 0 HV\_OVP: HV over voltage protection

0 = HV voltage normal

1 = HV over voltage protected

MFR\_ID\_B0B5 is the first 6 codes of the manufacturer's name (ASCII); MFR\_ID\_B6B11 is the last 6 codes of the manufacturer's name (ASCII) EX: manufacturer's name is MEANWELL  $\rightarrow$  MFR\_ID\_B0B5 is MEANWE; MFR\_ID\_B6B11 is LL

		MFR_II	D_B0B5		
Byte 0	Byte 1	Byte 2	Byte 3	Byte 4	Byte 5
0x4D	0x45	0x41	0x4E	0x57	0x45

		MFR_ID	_B6B11		
Byte 0	Byte 1	Byte 2	Byte 3	Byte 4	Byte 5
0x4C	0x4C	0x20	0x20	0x20	0x20

MFR\_MODEL\_B0B5 is the first 6 codes of the manufacturer's model name (ASCII); MFR\_MODEL\_B6B11 is the last 6 codes of the manufacturer's model name (ASCII);

EX: Model name is BIC-2200-24  $\rightarrow$  MFR\_MODEL\_B0B5 is BIC-22; MFR MODEL B6B11 is 00-24

MFR_MODEL_B0B5					
Byte 0	Byte 1	Byte 2	Byte 3	Byte 4	Byte 5
0x42	0x49	0x43	0x2D	0x32	0x32

MFR_MODEL_B6B11					
Byte 6	Byte 7	Byte 8	Byte 9	Byte 10	Byte 11
0x30	0x30	0x2D	0x32	0x34	0x20

MFR\_REVISION\_B0B5 is the firmware revision (hexadecimal). A range of 0x00 (R00.0)  $\sim$  0xFE (R25.4) represents the firmware version of an MCU; 0xFF represents no MCU existed

EX: The supply has two MCUs, the firmware version of the MCU number 1 is version R25.4 (0xFE), the MCU number 2 is version R10.5 (0x69)

Byte 0	Byte 1	Byte 2	Byte 3	Byte 4	Byte 5
0xFE	0x69	0xFF	0xFF	0xFF	0xFF

 $MFR\_DATE\_B0B5 \ is \ manufacture \ date \ (ASCII)$ 

EX: MFR\_DATE\_B0B5 is 180101, meaning 2018/01/01

Byte 0	Byte 1	Byte 2	Byte 3	Byte 4	Byte 5
0x31	0x38	0x30	0x31	0x30	0x31

MFR\_SERIAL\_B0B5 and MFR\_SERIAL\_B6B11 are defined as manufacture date and manufacture serial number (ASCII)

EX: The first unit manufactured on 2018/01/01  $\rightarrow$  MFR\_SERIAL\_B0B5:

180101; MFR\_SERIAL\_B6B11:000001

		MFR_II	D_B0B5		
Byte 0	Byte 1	Byte 2	Byte 3	Byte 4	Byte 5
0x31	0x38	0x30	0x31	0x30	0x31

			MFR_ID	_B6B11		
)	Byte 6	Byte 7	Byte 8	Byte 9	Byte 10	Byte 11
	0x30	0x30	0x30	0x30	0x30	0x31

#### SCALING\_FACTOR:

Byte 4~5	Bit 7~Bit 0							
Definition								
Byte 3	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Definition		-	-			IIN F	actor	
Byte 2	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Definition		-	-		Т	EMPERATU	JRE_1 Facto	or
Byte 1	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Definition		FAN_SPE	ED Factor			VIN F	actor	
Byte 0	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Definition		IOUT	Factor			VOUT	Factor	

#### byte 0:

### Bit 0:3 VOUT Factor: The Factor of DC voltage

0x0=DC voltage relevant commands not supported

0x4 = 0.001

0x5 = 0.01

0x6 = 0.1

0x7 = 1.0

0x8 = 10

0x9 = 100

#### Bit 4:7 **IOUT Factor: The Factor of DC current**

0x0=DC current relevant commands not supported

0x4 = 0.001

0x5 = 0.01

0x6 = 0.1

0x7 = 1.0

Λ, 1.0

0x8 = 10

0x9 = 100

Bit 0:3	VIN Factor : The Factor of AC voltage
	0x0=AC voltage relevant commands not supported
	0x4=0.001
	0x5=0.01
	0x6 = 0.1
	0x7 = 1.0
	0x8=10
	0x9 = 100
Bit 4 : 7	FAN_SPEED Factor: The Factor of fan speed
	0x0=Fan speed relevant commands not supported
	0x4=0.001
	0x5=0.01
	0x6=0.1
	0x7 = 1.0
	0x8=10
	0x9=100
byte 2 :	
Bit 0:3	TEMPERATURE_1 Factor: The Factor of internal ambient
	temperature
	0x0=internal ambient temperature relevant commands not
	supported
	0x4=0.001
	0x5=0.01
	0x6=0.1
	0x7 = 1.0
	0x8 = 10
. د مداما	0x9 = 100
byte 3 : Bit 0 : 3	IIN Factor . The Factor of A.C. comment
BILU:3	IIN Factor: The Factor of AC current
	0x0=AC current relevant commands not supported 0x4=0.001
	0x5 = 0.01
	0x6=0.1
	0x7 = 1.0
	0x8=10
	0x9=100

byte 1:

#### SYSTEM\_STATUS:

High byte	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit1	Bit 0
Definition								
Low byte	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit1	Bit 0
Definition		EEPER	INITIAL _STATE	ADL_ON		PFC_OK	DC_OK	M/S

### Low byte:

0 = Current device is Slave

1 = Current device is Master

### Bit 1 DC\_OK : Secondary DD output voltage status

0 = Secondary DD output voltage status TOO LOW 1 = Secondary DD output voltage status NORMAL

### Bit 2 PFC\_OK : Primary PFC status

0 = Primary PFC OFF or abnormal

1 = Primary PFC ON normally

### Bit 4 ADL\_ON : Active dummy load control status

0 = Active dummy load off/function not supported

1 = Active dummy load on

#### Bit 5 INITIAL\_STATE: Device initialized status

0 = In initialization status

1 = NOT in initialization status

#### Bit6 EEPER: EEPROM data access error

0 = EEPROM data access normal

1 = EEPROM data access error

 $\ensuremath{\mathbb{X}}$  When an EEPROM data access error occurs, the supply shuts down and then entering protection mode with the LED indicator off.

It only can be recovered after the EEPROM error condition is

resolved.

 $0xA \sim 0xF = Reserved$ 

#### SYSTEM\_CONFIG:

High byte	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit1	Bit 0
Definition								
Low byte	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit1	Bit 0
Definition						OPERATI	ON_INIT	CAN_CTRL

Low byte:

Bit 0 CAN CTRL : CANBus communication control status

0 = The output voltage/current defined by control over SVR

1 = The output voltage, current, ON/OFF control defined by control

over CANBus (VOUT\_SET, IOUT\_SET, OPERATION)

Bit1:2 OPERATION\_INIT: Pre-set value of power on operation command

0b00 = Power OFF, pre-set 0x00(OFF)

0b01 = Power ON, pre-set0x01(ON)

0b10 = Pre-set is previous set value

0b11 = not used, reserved

#### BIDIR CONFIG:

High byte	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit1	Bit 0
Definition								
Low byte	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit1	Bit 0
Definition								MODE

Low byte:

Bit 0 MODE: Bidirectional mode configuration

0 = Bi-direction auto-detect mode. DIR\_CTRL and C/D control (analogy) UN-controllable.

1 = Bi-direction battery mode. DIR\_CTRL and C/D control (analogy) controllable

#### 5.10.4 CANBus value range and tolerance:

### (1)Display parameters

(	CANBus Command		Display value range	Tolerance
0x0050	READ_VIN	ALL	180~264V	±10V
		12V	0~15V	±0.12V
0x0060	READ VOUT	24V	0~28V	±0.24V
0x0060	KEAD_VOOT	48V	0~56V	±0.48V
		96V	0~112V	±0.96V
		12V	-180~216A	±4A
0x0061	READ_IOUT	24V	-90~108A	±2A
000001		48V	-45~54A	±1A
		96V	-22.5~27A	±0.5A
0x0062	READ_TEMPERATURE_1	ALL	-40~110°C	±5°C

### (2)Control parameters (Bi-direction auto-detect mode)

CANBus Command		Model	Adjustable range	Tolerance	Default
0x0000	OPERATION	ALL	00h(OFF)/01h(ON)	N/A	01h(ON)
		12V	10~15V	±0.12V	12V
0x0020	VOUT SET	24V	19~28V	±0.24V	24V
UXUU2U	VO01_3E1	48V	38~65V	±0.48V	48V
		96V	76~112V	±0.96V	96V
		12V	10~15V	±0.12V	12V
0x0120	REVERSE_VOUT_SET	24V	19~28V	±0.24V	24V
UXU12U		48V	38~65V	±0.48V	48V
		96V	76~112V	±0.96V	96V
	IOUT_SET	12V	+36~+198A	±4A	198A
0x0030		24V	+18~+99A	±2A	99A
0x0030		48V	+9~+49.5A	±1A	49.5A
		96V	+4.5~+24.75A	±0.5A	24.75A
		12V	-153 ~-36A	±4A	-153A
0x0130	REVERSE_IOUT_SET	24V	-76.5~-18A	±2A	-76.5A
UXU130		48V	-38.3~-9A	±1A	-38.3A
		96V	-19.1~-4.5A	±0.5A	-19.1A
0x0140	BIDIRECTIONAL_CONFIG	ALL	00h(CV)/01h(Battery)	N/A	00h(CV)
0x00C2	SYSTEM_CONFIG	ALL	N/A	N/A	02h

#### (3)Control parameters (Bi-direction battery mode)

` ,	,				
	CANBus Command	Model	Adjustable range	Tolerance	Default
0x0000	OPERATION	ALL	00h(OFF)/01h(ON)	N/A	01h(ON)
0x0001	DIRECTION_CTRL	ALL	00h(Charge)/ 01h(Discharge)	N/A	00h(Charge)
		12V	10~15V	±0.12V	12.6V
0x0020	VOUT SET	24V	19~28V	±0.24V	25.2V
0X0020	VOU1_3E1	48V	38~65V	±0.48V	50.4V
		96V	76~112V	±0.96V	100.8V
0x0120	REVERSE_VOUT_SET	12V	10~15V	±0.12V	10V
		24V	19~28V	±0.24V	19V
		48V	38~65V	±0.48V	38V
		96V	76~112V	±0.96V	76V
	IOUT_SET	12V	+36~+160A	±4A	160A
0x0030		24V	+18~+80A	±2A	80A
0x0030		48V	+9~+40A	±1A	40A
		96V	+4.5~+20A	±0.5V	20A
		12V	-120 ~-36A	±4A	-120A
00120	REVERSE_IOUT_SET	24V	-64.3~-18A	±2A	-64.3A
0x0130		48V	-32.2~-9A	±1A	-32.2A
		96V	-16.1A~-4.5A	±0.5V	-16.1A
0x0140	BIDIRECTIONAL_CONFIG	ALL	00h(AD)/01h(BAT.)	N/A	00h(AD)
0x00C2	SYSTEM_CONFIG	ALL	N/A	N/A	02h
UXUUC2	3131EM_CONFIG	ALL	IN/A	IN/A	021

### 5.11 Restore Factory Default Setting

Users could set the device into factory default by following steps (command 0x0000, 0x0020, 0x0120, 0x0030, 0x0130, 0x0140, 0x00C2):

- (1) Set all DIP switch positions (device address) to ON
- (2) Power on in REMOTE OFF mode (no output at this step)
- (3) After power on, in 15 seconds, switch all DIP switch from ON to OFF and then switch ALL back to ON position.
- (4) Green LED will blink 3 times if set successfully
- (5) Factory default setting will be restored after re-power on. DIP switch diagram is as shown below.



# 6. Protections and Trouble Shooting

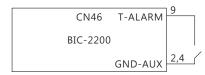
#### 6.1.1 Anti-islanding Protections

BIC-2200 is designed to refer to IEC 62116(2008), the supply shuts off within 2 seconds when AC is cut or abnormal. Please be aware that it is necessary to install an AC circuit breaker that complies with grid-tie standard in your country before the supply.

#### 6.1.2 Over Temperature Protection (OTP) and Alarm

Built-in thermal detection circuit, once the internal temperature exceeds a threshold value, the supply will shut down automatically (the fans will still be running to cool down the supply). Please switch off the supply, remove all possible causes and then leave the supply cooling down to a normal working temperature (approximate 10 minutes - 1 hour) before repower on again.

Maximum output current 4mA.



CN46 T-ALARM to GND-AUX	Condition
-0.5~0.5V	Normal Temp.
4.5~5.5V	Abnormal temp.

#### 6.1.3 AC Fail Protection

When AC voltage/frequency is abnormal, BIC-2200 will enter protection mode to prevent damaging itself or affect quality of the grid no matter which conversion it is, D/A or A/D. The supply will restore automatically when AC voltage/frequency back to normal.

#### 6.1.4 Short Circuit Protection

When there is short circuit at AC/DC end of BIC-2200, the supply will enter protection mode and shut down. Repower on to restore after short-circuit condition is resolved.

#### 6.1.5 Over Current Protection

In AC to DC conversion, when the load current exceeds  $110\% \pm 5\%$  of the rated current, protection mode will be triggered. Repower on to restore after over-current condition is resolved.

#### 6.1.6 DC Over Voltage Protection

When the DC end voltage is too high, the DC over-voltage protection circuit will be triggered. Repower on to restore after over-voltage condition is resolved.

### 6.2 Trouble Shooting

Failure State	Possible Cause	Suggested Solution		
The supply is not working	Remote OFF	Make sure remote ON/OFF is connected to +5V		
AC/DC or DC/AC conversion is incorrect	The setting voltage doesn't match actual DC end voltage	If it is bi-direction auto-detect mode, please refer to 5.1.2. If it is bi-direction battery mode, please refer to 5.1.3.3		
	The ambient temperature too high	Re-start the supply after temperature dropped back		
	DC load current too high	Re-start the supply after reducing DC load current		
LED shows abnormal indication	AC voltage/frequency abnormal	Re-start the supply after AC voltage/frequency is within a normal range		
	Battery or load voltage too high	Re-start the supply after DC end voltage is within a normal range		

If you are unable to clarify the problem you are facing, please contact MEAN WELL or any of our distributors for repair service.

### 7. Warranty

This product provides five years warranty under normal usage. Do not replace parts or any form of modification to the product in order to keep the warranty effectively.

MEAN WELL possesses the right to adjust the content of this manual.
 Please refer to the latest version of our manual on our website.
 https://www.meanwell.com







#### 明緯企業股份有限公司 MEAN WELL ENTERPRISES CO., LTD.

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